SECTION 1—GENERAL DESCRIPTION

1-1. TRANSMISSION

The 1000 and 2000 Product Families Electronic Controls system features closed-loop clutch control to provide superior shift quality over a wide range of operating conditions. The 1000 and 2000 Product Families configurations can be programmed to provide five forward speeds, neutral, and reverse. The fifth range has an overdrive gear ratio. The 1000 and 2000 Product Families incorporate a variety of standard and optional design features.

Figure 1–1 is a block diagram of the basic system inputs and outputs.



Figure 1- Tigasmission Control Module Block Diagram

Figure 1–2 shows the electronic components.

Electronic Controls consist (f) le following elements:

- Remote 10V 24V Sealed Transmission Control Module (TCM)
- Throttle P is on Sensor (TPS), electronic engine throttle data, or PWM signal
- Spr zu Se...sors Input (Engine), Turbine, and Output
- Control Jalve Assembly (Electro-Hydraulic Valve Body)
- < NS U Switch
- essure Switch Manifold (PSM)
- Winng Harnesses

NOTE: All external harnesses are OEM-supplied.



Figure 1–2. Electronic Control Components

1–2. TRANSMISSION CONTROL MODULE (TCM)

The electronic control of the transmission is performed by a microcomputer. The microcomputer is an independent controller and is referred to as a Transmission Control Module (TCM). TCMs are available in both 12V and 24V configurations to match the configuration of the vehicle electrical system.

The TCM (Figure 1–3) receives and processes signals from various switches and sensors. The TCM determines shift sequences, shift timing, and clutch apply and release pressures. The TCM uses the information to control transmission solenoids and valves, supply system status, and provide diagnostic information.



Figure 1–3. Trans. sion Control Module (TCM)

1–3. SHIFT SELECTOR

The vehicle is equipped with a lever-type s, 'ft selector (Figure 1–4). In addition to the lever assembly provided for the operator, other components a contact with the shift selector are the manual selector value in the main control value body and an NSBU switch hould be on the selector shaft. Shift selector components (with the exception of the transmission selector shaft, are customer-supplied.

A. Shift Selector Runge Positions

The ormate hooses the transmission range by moving the selector lever to the appropriate gate point in (Figure 1–4). When properly adjusted, the shifter gates prevent inadvertent shifting between anges and correspond to the internal transmission detent positions. A positive detent is provided in the transmission to maintain the selector shaft in the selected position.



Figure 1–4. Typical Lever-Type Shift Selector

The TCM shift calibration determines the available forward ranges for each selector position. Although specific installations vary, typical selector positions for the 1000 and 2000 Product Families are:

P — Park. Parking pawl or parking brake is engaged, if available. This position is not available on all shift selectors.

R — Reverse.

N — Neutral. May be used when starting the engine and for stationary operations. The NSBU Switch disables the starter switch if a range other than N (Neutral) or P (Park) is selected before starting the vehicle.

OD — Overdrive. The highest forward range used for normal driving. The transmission shifts to first range for starting, then automatically upshifts through the ranges (as operating conditions permit) until the highest range is attained.

D, **2**, **1** — Forward Range. The transmission shifts to first range for starting. The range selected on the shift selector is the highest range which will at ined during automatic shifting.

B. Manual Selector Valve

The manual shift selector shaft is attached to the nanual selector valve within the transmission main control valve body. The selector valve has three positions: Reverse, Neutral, and Forward.

NOTE: For transmissions equir red with a Park position, the selector valve remains in the Neutral position where a selector is moved to Park.

The Neutral and Reverse sector alve positions (refer to Appendix H—Hydraulic Schematics) exhaust the C1 and C2 on ing clutches. By exhausting C1 and C2 clutches, forward range is inhibited. This proverse be capability for the operator to override the electronically commanded ranges if **N** (Neutral) required.

C. NSBU Switch

The instal" a on Ca transmission-mounted neutral start/reverse signal switch is required. This switch, coming ity called an "NSBU Switch" (Figure 1–5), mounts directly onto the transmission housing from the outside and detects the angular position of the shift selector shaft. This position is communicated to the TCM so that certain vehicle control functions can be continated with the position of the shift controls. The NSBU switch has redundant circuitry to a prt the TCM in the event of a single wire or switch failure.

he neutral signal output of the NSBU switch is typically used as confirmation that the transmission is in **N** (Neutral) before the engine starter is engaged. The NSBU switch is interfaced to the starter circuit with weatherproof electrical connectors. The reverse signal provision may be used to activate vehicle back-up lights and/or reverse warning devices.



Figure 1–5. NSBU Switch

1-4. THROTTLE POSITION SENSOR

The Throttle Position Sensor (TPS) can be mounted to the engine, chassis, or transmission. The TPS (Figure 1–6) contains a pull actuation cable and a potentiometer. One end of the cable is attached to the engine fuel lever and the other, inside a protective housing, to the TPS potentiometer. Output voltage from the TPS is directed to the TCM through the external harness. The voltage signal indicates the throttle position and, in combination with other input data, determines shift timing.



Figure 1–6 Throttle Position Sensor

1–5. SPEED SENSORS

There are three speed sensors available for rece with 1000 and 2000 Product Families transmissions: the input (engine) speed sensor, the turbine speed on sor, and the output speed sensor (Figure 1–7). The speed sensors provide rpm information to the TCM The speed ratios between the various sensors allow the TCM to determine the transmission operating range. Speed ensor information is also used to control the timing of clutch apply pressures, resulting in the best poends with quality.



Figure 1–7. Typical Speed Sensor

The speed sensors are variable reluctance devices which convert mechanical motion to an AC voltage. Each sensor consists of a wire coil wrapped around a pole piece that is adjacent to a permanent magnet. These elements are contained in a housing which is mounted adjacent to a rotating ferrous member (such as a gear tooth). Two signal wires extend from one end of the housing and an exposed end of the pole piece is at the opposite end of the housing. The permanent magnet produces lines of flux around the pole piece. As a ferrous object (such as a gear tooth) approaches and passes through the gap at the end of the pole piece, an AC voltage pulse is induced in the wire coil. The TCM calculates the frequency of these AC pulses and converts it to a speed value. The AC voltage generated varies from 150mV at low speed to 15V at high speed. The signal wires from the sensor are formed as twisted pairs to cancel magnetically induced fields. The cable is also shielded to protect from voltage-related fields. Noise from other sources is eliminated by using two-wire differential inputs at the TCM.

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